Degenerate hyperbolicity in cellular automata

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- In a linear continuous-time dynamical system $\dot{\mathbf{x}} = A\mathbf{x}$, if $\mathbf{x} : \mathbb{R} \to \mathbb{R}^n$ and A is a real $n \times n$ matrix with all eigenvalues distinct and having negative real parts, $\mathbf{x}(t) \to 0$ exponentially fast as $t \to \infty$.
- The same phenomenon can be observed in nonlinear system $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x})$ (where $\mathbf{f} : \mathbb{R}^n \to \mathbb{R}^n$) in a vicinity of hyperbolic fixed point, as long as the Jacobian matrix of \mathbf{f} evaluated at the fixed point has only distinct eigenvalues with negative real parts.
- Discrete dynamical systems exhibit similar behaviour.

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If eigenvalues are degenerate (repeated), the convergence is linear-exponential. Example:

$$\begin{bmatrix} x_{n+1} \\ y_{n+1} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{1}{4} & 1 \end{bmatrix} \begin{bmatrix} x_n \\ y_n \end{bmatrix}$$
(1)

is defined by a matrix which has degenerate (double) eigenvalue $\frac{1}{2}$,

$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = \left(\frac{1}{2}\right)^n \begin{bmatrix} 1-n & 2n \\ -\frac{n}{2} & 1+n \end{bmatrix} \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$$
(2)

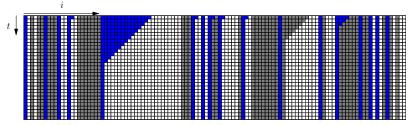
We will consider 3-state nearest-neighbour CA obtained from elementary binary CA by "lifting" them to 3-states. Let $g: \{0,1\}^3 \rightarrow \{0,1\}$ be a local function of elementary CA satisfying g(0,0,0) = 0, g(1,1,1) = 1, and let $f_g: \{0,1,2\}^3 \rightarrow \{0,1,2\}$ be defined by

$$f_g(x_1, x_2, x_3) = \begin{cases} g(x_1, x_2, x_3), & x_1, x_2, x_3 \in \{0, 1\} \\ 2g\left(\frac{x_1}{2}, \frac{x_2}{2}, \frac{x_3}{2}\right), & x_1, x_2, x_3 \in \{0, 2\} \\ g(x_1 - 1, x_2 - 1, x_3 - 1) + 1, & x_1, x_2, x_3 \in \{1, 2\} \\ x_2, & \text{otherwise.} \end{cases}$$

One of the most interesting cases is f_g defined by g being the elementary CA rule 140, given by

$$g(x_1, x_2, x_3) = x_2 - x_1 x_2 + x_1 x_2 x_3$$

for $x_1, x_2, x_3 \in \{0,1\}.$ Rule f_g has the following spatio-temporal pattern:



Let \mathcal{B} be the set off all finite blocks (words). A *block evolution* operator corresponding to f is a mapping $\mathbf{f} : \mathcal{B} \mapsto \mathcal{B}$ defined as follows. Let $a = a_0 a_1 \dots a_{n-1} \in \mathcal{B}$ where $n \ge 3$. Then

$$\mathbf{f}(a) = \{f(a_i, a_{i+1}, \dots, a_{i+2})\}_{i=0}^{n-3}.$$

Example: for 3-state rule 140, $f^4(202112011110210201) = 120100002$,

A given block b has typically more than one preimage under f. Let the *density polynomial* associated with a string $b = b_1 b_2 \dots b_n$ be defined as

$$\Psi_{\mathbf{b}}(p,q,r) = p^{\#_0(\mathbf{b})} q^{\#_1(\mathbf{b})} r^{\#_2(\mathbf{b})},\tag{3}$$

where $\#_i(\mathbf{b})$ is the number of occurrences of symbol i in \mathbf{b} . If A is a set of binary strings, we define density polynomial associated with A as

$$\Psi_A(p,q,r) = \sum_{\mathbf{a}\in A} \Psi_{\mathbf{a}}(p,q,r).$$
(4)

One can show that if one starts with a bi-infinite string of symbols drawn from Bernoulli distribution where probabilities of 0, 1 and 2 are, respectively, p, q and r, then the expected fraction of sites in state k after n iterations of rule f is given by

$$\Psi_{\mathbf{f}^{-n}(k)}(p,q,r)$$

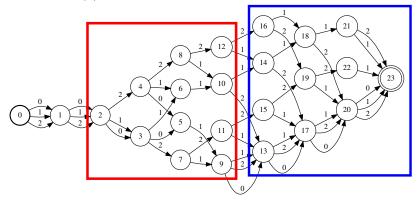
This quantity will be called *density* of symbols k after n iterations of f.

In order to find a "closed form" expression for the density, we need to describe the structure of preimage sets $\mathbf{f}^{-n}(k)$. These sets grow very quickly. For example, for rule 140, $\mathbf{f}^{-4}(1)$ has 6048 elements. Some of them:

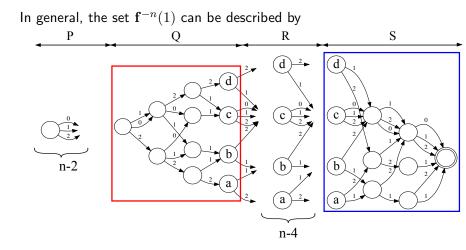
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The set $f^{-4}(1)$ can be described by FSM:



General FSM



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Using the FSM, one can construct density polynomial,

$$\begin{split} \Psi_{\mathbf{f}^{-n}(1)}(p,q,r) &= \frac{pq^2 \left(-pr+pq+q^2\right) (q\lambda)^n}{\lambda^2 \left(p+r\right) \left(q-r\right)} \\ &+ \frac{qr \left(-p^2r+p^2q+pq^2-2 \, pqr+r^3-q^2r\right) (r\lambda)^n}{\lambda^2 \left(p+q\right) \left(q-r\right)} \\ &+ \frac{q \left(p^3+p^2q+2 \, p^2r+pr^2+3 \, pqr+r^3+r^2q+q^2r\right) \lambda^{2n}}{\lambda \left(p+r\right) \left(p+q\right)}, \end{split}$$

where we used $\lambda = p + q + r$.

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$$\begin{split} \Psi_{\mathbf{f}^{-n}(1)}(p,q,q) &= \frac{pq^3(n+1) (q\lambda)^n}{\lambda^2 (q+p)} \\ &+ \frac{q^2 \left(2 \, p^3 + 4 \, p^2 q + p q^2 - 2 \, q^3\right) (q\lambda)^n}{(q+p)^2 \, \lambda^2} \\ &+ \frac{\left(p^3 + 3 \, p^2 q + 4 \, p q^2 + 3 \, q^3\right) q\lambda^{2n}}{\lambda \left(q+p\right)^2}, \end{split}$$

When p = 1, q = 1 and r = 1, then $\Psi_{\mathbf{f}^{-n}(1)}(1, 1, 1)$ counts the number of preimages of 1. This yields a sequence exhibiting linear-exponential growth,

$$\Psi_{\mathbf{f}^{-n}(1)}(1,1,1) = \left(\frac{n}{18} + \frac{7}{36}\right)3^n + \frac{11}{12}9^n.$$

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- What is the meaning of the degeneracy?
- Does it mean that dynamics of rule 140 (or other rules) can be effectively reduced to a finite-dimensional system of difference equations?
- Does it mean that local structure approximation becomes exact at some level for rule 140? Or for other rules?