

Group-Walking Automata

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Introduction

Our Model

Our Results

Future Work

Different Kinds of Finite Automata

Group-Walking
Automata

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Introduction

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Future Work

- ▶ One-way finite automata on words
- ▶ Two-way finite automata on words
- ▶ Four-way finite automata on pictures
- ▶ Automata that walk on trees or *graphs*

Different Kinds of Finite Automata

- ▶ One-way finite automata on words
- ▶ Two-way finite automata on words
- ▶ Four-way finite automata on pictures
- ▶ Automata that walk on trees or *graphs*
- ▶ In this presentation: Cayley graphs of finitely generated infinite groups

Cayley Graphs

- ▶ Take a group (G, \cdot) generated by $S = \{g_1, \dots, g_n\}$
- ▶ We usually assume S *symmetric*: if $g \in S$ then $g^{-1} \in S$
- ▶ The *Cayley graph* of G has vertex set G and edges $g \rightarrow g \cdot g_i$ for $i = 1, \dots, n$
- ▶ It is infinite if G is, and every vertex has degree n

Cayley Graphs

Example: the discrete plane \mathbb{Z}^2

• $(-2, 2)$ • $(-1, 2)$ • $(0, 2)$ • $(1, 2)$ • $(2, 2)$

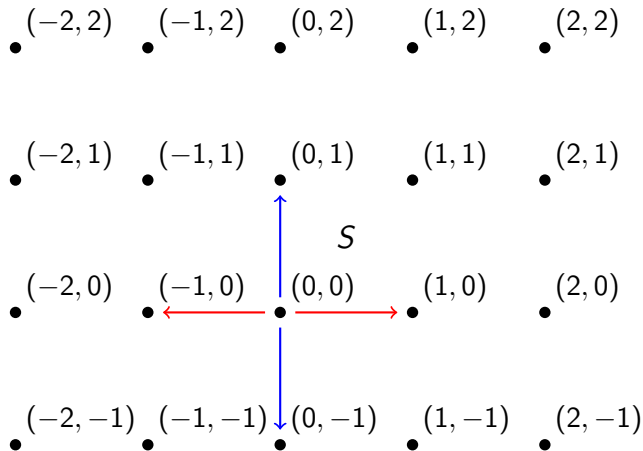
• $(-2, 1)$ • $(-1, 1)$ • $(0, 1)$ • $(1, 1)$ • $(2, 1)$

• $(-2, 0)$ • $(-1, 0)$ • $(0, 0)$ • $(1, 0)$ • $(2, 0)$

• $(-2, -1)$ • $(-1, -1)$ • $(0, -1)$ • $(1, -1)$ • $(2, -1)$

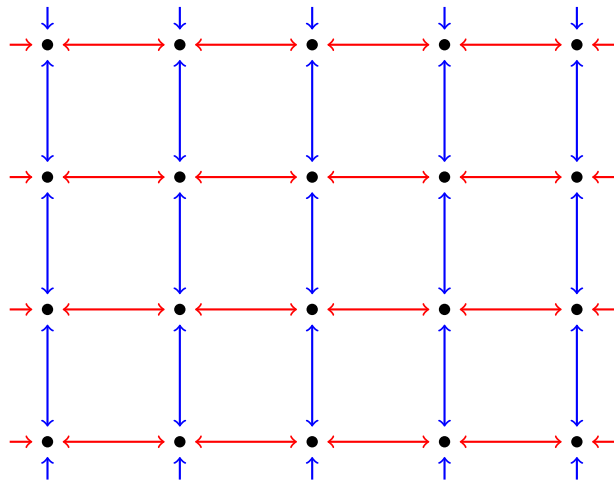
Cayley Graphs

Example: the discrete plane \mathbb{Z}^2



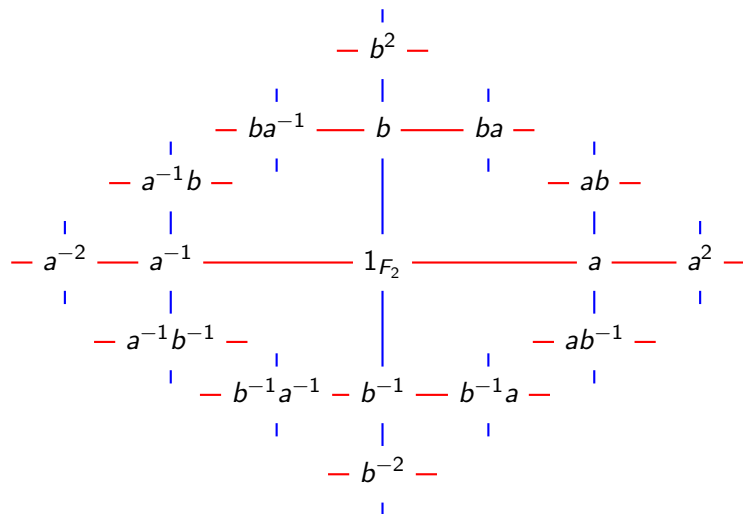
Cayley Graphs

Example: the discrete plane \mathbb{Z}^2



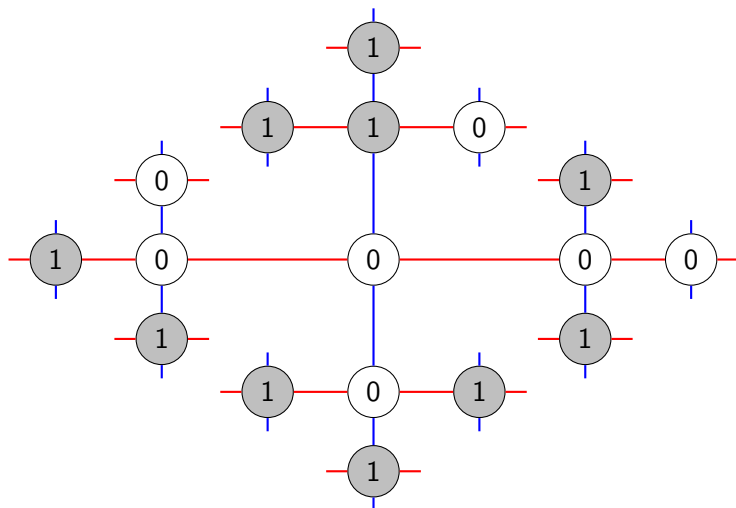
Cayley Graphs

Example: the free group $F_2 = \langle a, b \rangle$



Cayley Graphs

Example: the free group $F_2 = \langle a, b \rangle$, with vertex coloring



Definition (Group-Walking Automaton)

- ▶ A *group-walking automaton* is a multi-head finite automaton that walks on the Cayley graph of G
- ▶ It recognizes vertex colorings of G
- ▶ A coloring is *rejected* if, started from *some* single vertex in *some* initial states, the heads eventually return together and enter a rejecting state
- ▶ The class of all sets of colorings accepted by automata (with k heads) is $\mathcal{S}(G)$ ($\mathcal{S}(G, k)$)

Group-Walking Automata

The heads of group-walking automata *can*:

- ▶ Take synchronized steps of variable length along the edges of the graph
- ▶ Read the colors of the vertices, and the states of other heads on the same vertex
- ▶ Change their internal state

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- ▶ Take synchronized steps of variable length along the edges of the graph
- ▶ Read the colors of the vertices, and the states of other heads on the same vertex
- ▶ Change their internal state

They *cannot*:

- ▶ Take arbitrarily long steps
- ▶ Read the colors of faraway vertices, or the states of faraway heads
- ▶ Change the colors of the vertices

- ▶ Every set of colorings in $\mathcal{S}(G)$ is defined by *forbidden finite patterns*: it is a G -subshift
- ▶ Which subshifts are in $\mathcal{S}(G, k)$ for different k ? How does this depend on G ?
- ▶ On *finite* words, trees and grids, we have infinite hierarchies: adding more heads increases the model's power

V.S. & I.T.: *Plane-Walking Automata* (presented at AUTOMATA 2014, Himeji, Japan)

- ▶ $\mathcal{S}(\mathbb{Z}^d, 3) = \mathcal{S}(\mathbb{Z}^d)$, contains exactly the Π_1^0 subshifts
- ▶ $\mathcal{S}(\mathbb{Z}^d, 1) \subsetneq \mathcal{S}(\mathbb{Z}^d, 2) \subseteq \mathcal{S}(\mathbb{Z}^d, 3)$; second inclusion strict for $d \geq 3$, unknown for $d \leq 2$

Π_1^0 (or *effectively closed*) subshifts have computable sets of forbidden patterns

Theorem (Three Heads)

If G is not torsion, then $\mathcal{S}(G, 3)$ contains all Π_1^0 subshifts; if G also has decidable word problem, then the classes coincide and $\mathcal{S}(G) = \mathcal{S}(G, 3)$

- ▶ *Proof idea:* Simulate a certain type of Turing-universal counter machine on the Cayley graph using 3 heads

Theorem (Characterization of Torsion Groups)

For all G , every subshift in $\mathcal{S}(G)$ is intrinsically Π_1^0 ; the classes coincide iff $\mathcal{S}(G) = \mathcal{S}(G, 4)$ iff G is not torsion

- ▶ Intrinsically Π_1^0 subshifts have sets of forbidden patterns computable from the word problem of G
- ▶ G is a torsion group if every $g \in G$ has finite order: $g^n = 1_G$ for some $n > 0$
- ▶ *Proof idea:* In non-torsion case, decide word problem with 4 heads; walking on torsion group results in a loop

Definition (Arithmetical Program)

An *arithmetical program* is a one-head finite automaton equipped with an unbounded *counter*, and it can

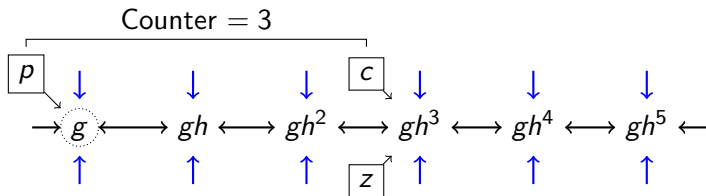
- ▶ walk on the Cayley graph of G and read its colors
- ▶ increment and decrement the counter
- ▶ check the remainder of the counter modulo fixed positive integers, and whether it is 0
- ▶ multiply or divide the counter by fixed positive integers
- ▶ reject the coloring at any point

Arithmetical programs recognize exactly the Π_1^0 subshifts

Three Heads

Simulating an arithmetical program with 3 heads:

- ▶ $h \in G$ has infinite order
- ▶ counter value is distance between p and c in powers of h
- ▶ multiplication, division and movement are implemented using synchronized signals and the z head



Four Heads

- ▶ With a fourth head we can solve the word problem of G
- ▶ For a product of generators $g_{i_1} \cdots g_{i_n}$, leave the fourth head behind and walk along the g_{i_j} with the others
- ▶ If they return to the fourth head, $g_{i_1} \cdots g_{i_n} = 1_G$
- ▶ Then we can recognize all intrinsically Π_1^0 subshifts

Torsion Groups

- ▶ Finitely generated infinite torsion groups are hard to construct (*Burnside Problem*)
- ▶ In a torsion group, a single head walking in any direction ends up in a loop

Lemma (Navigation on Torsion Groups)

Let G be a torsion group. There exists $d_G : \mathbb{N}^3 \rightarrow \mathbb{N}$ such that for all k -head q -state automata that can take steps of length r , no head can move more than $d_G(k, q, r)$ steps away from its starting point on the all-0 coloring of G .

Proof by induction on k

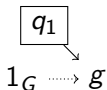
Torsion Groups

First case: one head ($k = 1$)



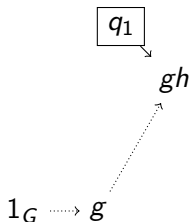
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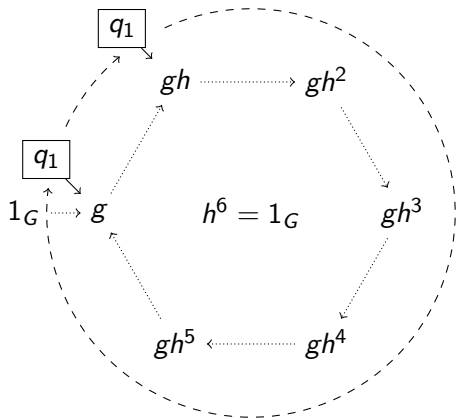
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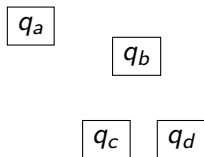
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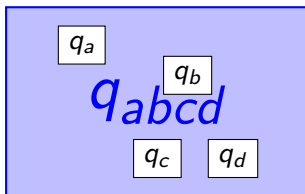
Torsion Groups

Second case: all heads stay close to each other



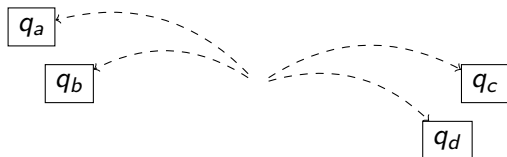
Torsion Groups

Second case: all heads stay close to each other
Combine into one head with larger state set, and reduce to
the $k = 1$ case



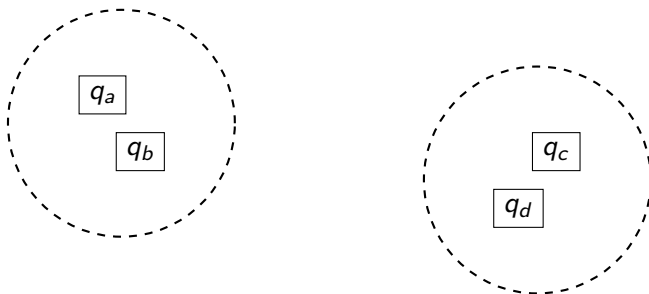
Torsion Groups

Third case: some heads travel far from others



Torsion Groups

Third case: some heads travel far from others
Apply induction hypothesis to every separated group: they
never communicate again and travel a bounded distance



Corollary

If G is a torsion group, then the subshift of colorings $x : G \rightarrow \{0, 1\}$ with $\#\{g \in G \mid x_g = 1\} \leq 1$ is not in $\mathcal{S}(G)$

In particular, $\mathcal{S}(G)$ does not contain all intrinsically Π_1^0 subshifts

Future Work

We showed that $\mathcal{S}(G) = \mathcal{S}(G, 4)$ if G is not a torsion group,
and $\mathcal{S}(G) = \mathcal{S}(G, 3)$ if G also has a decidable word problem

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Conjecture (4 Heads Better than 3)

There exists a non-torsion group G such that
 $\mathcal{S}(G, 3) \subsetneq \mathcal{S}(G, 4)$

We showed that $\mathcal{S}(G) = \mathcal{S}(G, 4)$ if G is not a torsion group, and $\mathcal{S}(G) = \mathcal{S}(G, 3)$ if G also has a decidable word problem

Conjecture (4 Heads Better than 3)

There exists a non-torsion group G such that $\mathcal{S}(G, 3) \subsetneq \mathcal{S}(G, 4)$

Conjecture (Infinite Hierarchy)

There exists a torsion group G such that the hierarchy $\mathcal{S}(G, k)_{k \geq 1}$ is infinite

The End

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Thank you!